(NASA-CR-160517) RESULTS OF TESTS USING A 0.02-SCALE MODEL (89-OTS) OF THE SPACE SHUTTLE INTEGRATED VEHICLE IN THE AEDC 16-FOOT TRANSONIC PROPULSION WIND TUNNEL (IA156A), VOLUME 3 (ROCKWELL International

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VOLUME 3 of 3

RESULTS OF TESTS USING A 0.02-SCALE MODEL (89-OTS) OF

THE SPACE SHUTTLE INTEGRATED VEHICLE IN THE AEDC

16-FOOT TRANSONIC PROPULSION WIND TUNNEL (IA156A)

Ъу

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bу

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NASA Series Number:

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by

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ABSTRACT

An experimental investigation (Test IA156A) was conducted in the Arnold Engineering Development Center 16-Foot Transonic Propulsion Wind Tunnel from November 1, 1977 through November 10, 1977.

The objective of the test was to obtain force and moment data on all vehicle elements (orbiter, external tank, and each solid rocket booster), wing and vertical tail load indicators, elevon and rudder hinge moments, and base and body flap pressure data.

Data were obtained in the Mach number range from 0.3 to 1.55 with Reynolds numbers per foot of 2.7×10^6 to 3.5×10^6 . The test was conducted using angle-of-sideslip sweeps at fixed angles-of-attack. Angles-of-attack and sideslip were both within a range of plus and minus ten degrees, with the maximum angle being dependent upon the requirements at a particular Mach number.

Configuration variations consisted of a series of differential incoard/outboard elevon angle settings at zero aileron angle, with and without the Shuttle Infrared Leeside Temperature Sensing (SILTS) pod on the orbiter.

Force data presented in this report were provided by the facility on April 9, 1980 (Reference 3). Angles of attack and sideslip were corrected for flow angularities by the ARO personnel. Elevon deflection angles were corrected by Data Management Services (DMS) per RI Internal Letter SAS/AERO/78-221 (Reference 4) dated April 25, 1978. This data was initially released by DMS under special request project identification SPRT8N.

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INTRODUCTION

The 0.02-scale model (Model 89-0TS) of the space shuttle integrated vehicle was tested in the Arnold Engineering Development Center 16-Foot Transonic Wind Tunnel between November 1, 1977, and November 10, 1977. This test, designated IA156A, used a total of 124 occupancy hours in the facility.

Data were obtained at fixed angles-of-attack between -10 and +10 degrees over a degrees with angle-of-sideslip sweeps between -10 and +10 degrees over a Mach number range of 0.3 to 1.55. Four six-component balances were used to obtain vehicle element forces and moments. Three single-component balances were used to measure elevon (right wing only) and rudder hinge moments. Two three-component balances were used to measure wing (left side) and vertical tail normal force, bending moment, and torsion.

Model configuration variables were elevon deflection angle and Shuttle Infrared Leeside Temperature Sensing (SILTS) pod on or off. The orbiter was instrumented with 19 base pressure taps and 32 body flap taps. The external tank had 45 base pressure taps, and each SRB was instrumented with five base pressure taps.

This report provides a description of the test consisting of remarks on the conduct of the test, descriptions of the model and the test facility, details on test procedure, information on data reduction, and tabulated test results.

The flow angularity corrections for alpha and beta were revised after completion of this test. The force data presented in this text contains the final flow angularity corrected alpha and beta data (Reference 3). Elevon deflection angles were corrected for loads as specified in Reference 4.

This report consists of 2 volumes of force data and 1 volume of tabulated pressure data on microfiche. The volumes are arranged in the following manner:

VOLUME NUMBER	CONTENTS	MICROFICHE PAGE NUMBERS
1	IA156A FORCE DATA TABULATIONS	-
2	IA156A FORCE DATA TABULATIONS	~
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NOMENCLATURE

SYMBOL	MNEMONIC	DEFINITION
Tunn	el Parameters	
Part, Point		run identification
Project, Test		ARO, Inc. test identification
M	MACH	freestream Mach number
P T .	PT	freestream total pressure, psfa
P	P	freestream static pressure, psfa
Q	Q	freestream dynamic pressure, psf
Rex10 -6	RN/L	Reynolds number per foot
TT		freestream total temperature, OF
TTR		freestream total temperature, OR
0.02	-Scale Model Test	t Parameters
AFA		flow angularity in the tunnel pitch plane, positive up, degrees
ALFAL		launch vehicle angle-of-attack, degrees
ALFALS	ALPHAL	left hand side solid rocket booster angle- of-attack, degrees
ALFARS	ALPHAR	right hand side solid rocket booster angle- of-attack, degrees
ALFAT	ALPHAT	external tank angle-of-attack, degrees
BETAL		launch vehicle sideslip angle, degrees
BETALS	BETALS	left hand side solid rocket booster sideslip angle, degrees
BETARS	BETARS	right hand side solid rocket booster sideslip angle, degrees

SYMBOL	MNEMONIC	DEFINITION
	0.02-Scale Model Test	Parameters (Continued)
BETAT	BETAT	external tank sideslip angle, degrees
BFA		flow angularity in the tunnel cross flow plane, positive from right to left looking upstream, degrees
	0.02-Scale Left Hand	Side SRB Coefficients (Left Side SRB Balance)
CABLS	CABLS	base axial-force coefficient
CAFLS	CAFLS	forebody axial-force coefficient, CAIS-CABLS
CALS	CALS	total axial-force coefficient
CBLIS	CBLLS	rolling moment coefficient
CIMFLS	CIMFLS	pitching moment coefficient
CNFLS	CNFLS	normal force coefficient
CYFLS	CYFLS	side force coefficient
CYNBLS	CYNBLS	base yawing moment coefficient
CYNFIS	CYNFLS	forebody yawing moment coefficient, CYNLS-CYNBLS
CYNLS	CYNLS	total yawing moment coefficient
	0.02-Scale Right Hand	SRB Coefficients (Right Side SRB Balance)
CABRS	CABRS	base axial force coefficient
CAFRS	CAFRS	forebody axial force coefficient, CARS-CABRS
CARS	CARS	total axial force coefficient
CBLRS	CBLRS	rolling moment coefficient

SIMBOL	MNEMONIC	DEFINITION
	O.O2-Scale Right Hand (Continued)	SRB Coefficients (Right Side SRB Balance)
CIMFRS	CIMFRS	pitching moment coefficient
CNFRS	CNFRS	normal force coefficient
CYFRS	CYFRS	side force coefficient
CYNBRS	CYNBRS	base yawing moment coefficient
CYNFRS	CYNFRS	forebody yawing moment coefficient CYNRS - CYNBRS
CYNRS	CYNRS	total yawing moment coefficient
	0.02-Scale External T (External Tank Balance	ank + (SRB Right + SRB Left) Coefficients,
CABT	CABT	external tank base axial force coefficient
cafts	CAFTS	forebody axial force coefficient, CATS - (CABT + CABLS + CABRS)
CATS	CATS	total axial force coefficient
CBLFTS	CBLFTS	rolling moment coefficient
CIMTS	CIMFIS	pitching moment coefficient
CNFTS	CNFIS	normal force coefficient
CYFTS	CYFTS	side force coefficient
CYNFTS	CYNFTS	forebody yawing moment coefficient, CYMTS - (CYMBLS + CYMBRS)
CYNTS	CYNTS	total yawing moment coefficient
	0.02-Scale External T	ank Forebody Coefficients
CAFT	CAFT	forebody axial force coefficient, CAFTS - (CAFLS + CAFRS)

SYMBOL	MNEMONIC	DEFINITION
	0.02-Scale External T	ank Forebody Coefficients (Continued)
CBLFT	CBLFT	forebody rolling moment coefficient, CBLFTS - (CBLLS + CBLRS)
CIMFT	CLMFT	forebody pitching moment coefficient, CIMFTS - (CIMFIS + CIMFRS)
CNFT	CNFT	forebody normal force coefficient, CNFTS - (CNFLS + CNFRS)
CYFT	CYFT	forebody side force coefficient, CYFTS - (CYFIS + CYFRS)
CYNFT	CYNFT	forebody yawing moment coefficient, CYNFTS - (CYNFTS + CYNFRS)
	0.02-Scale Launch Veh	icle Coefficients (Orbiter Balance)
CABO	CABO	orbiter base axial force coefficient
CAFL	CAFL	forebody axial force coefficient, CAL - (CABO + CABT + CABLS + CABRS)
CAL	CAL	total axial force coefficient
CBLFL	CBLFL	rolling moment coefficient
CIMBO	CIMBO	orbiter base pitching moment coefficient
CIMFL	CIMFL	forebody pitching moment coefficient, CIML - CIMBO
CIML	CIML	total pitching moment coefficient
CNBO	CNBO	orbiter base normal force coefficient
CNFL	CNFL	forebody normal force coefficient, CNL - CNBO
CNL	CNL	total normal force coefficient
CYFL	CYFL	forebody side force coefficient

SYMBOL	MNEMONIC	DEFINITION
	O.02-Scale Launch Ve (Continued)	ehicle Coefficients (Orbiter Balance)
CYNFL	CYNFL	forebody yawing moment coefficient, CYNL - (CYNBIS + CYNBRS)
CYNL	CYNL	total yawing moment coefficient
	0.02-Scale Orbiter I	Forebody Coefficients
CAFO	CAFO	axial force coefficient, CAFL - CAFTS
CBLFO	CBLFO	rolling moment coefficient, CBLFL - CBLFTS
CIMFO	CLMFO	pitching moment coefficient, CIMFL - CIMFTS
CNFO	CNFO	normal force coefficient, CNFL - CNFTS
CYFO	CYFO	side force coefficient, CYFL - CYFTS
CYNFO	CYNFO	yawing moment coefficient, CYNFL - CYNFTS
	0.02-Scale Vertical	Tail Coefficients (See Figure le)
CBVT	CEVT	bending moment coefficient
CSVT	CNVT	side force coefficient
CTVT	CTVT	torsional moment coefficient
	0.02-Scale Wing Coet	fficients (See Figure 1b)
CBW	CBW	bending moment coefficient
CN W	CN W	normal force coefficient
CTW	C T W	torsional moment coefficient

SYMBOL	MNEMONIC	DEFINITION
	0.02-Scale Elevon and	Rudder Coefficients (See Figure 1f)
CHEI	CHEI	inboard elevon hinge moment coefficient
CHEO	CHEO	outboard elevon hinge moment coefficient
CHR	CHR	rudder hinge moment coefficient
	Model Geometric Nomen	clature
CL		centerline
ET		external tank
HL		hinge line
MRC		moment reference center
SRB		solid rocket booster
x/c _{BF}		ratio of a station on the body flap to the body flap chord (See Figure 2c)
x_B		SRB station
X _o /L _o		ratio of a station on the orbiter to the orbiter length
$\mathbf{x}_{\mathbf{T}}$		body station on the external tank
Yo		lateral station on the orbiter, positive to the right of the plane of symmetry (See Figure 2b)
z_{o}		orbiter water line (Figures 2a and 2b)
а	ALPHAO	orbiter angle-of-attack, degrees
β	BETAO	orbiter sideslip angle, degrees
δ e _I	IB-ELV	inboard elevon deflection angle, degrees (See Figure 1b)

SYMBOL	MNEMONIC	DEFINITION
<u>M</u>	lodel Geometri	c Nomenclature (Continued)
$^{\delta}$ e $_{o}$	OB-ELV	outboard elevon deflection angle, degrees (See Figure 1b)
ф	PHIO	rotational angle on model component surface (See Figure 2e), degrees
η		ratio of spanwise station on orbiter body flap to total span of body flap, positive from left to right (See Figure 2b)
ALFA Ø U	ALFAØ U	orbiter angle-of-attack, (uncorrected for flow angularity), degrees
ALPATU	ALPATU	external tank angle-of-attack (uncorrected for flow angularity), degrees
ALFLSU	ALFLSU	left SRB angle-of-attack (uncorrected for flow angularity), degrees
ALFRSU	ALFRSU	right SRB angle-of-attack (uncorrected for flow angularity), degrees
ALPHAI	ALPHAI	tunnel instrumentation indicated pitch attitude, degrees
BETA Ø U	BETAØU	orbiter sideslip angle (uncorrected for flow angularity), degrees
BETATU	BETATU	external tank sideslip angle (uncorrected for flow angularity), degrees
BETLSU	BETLSU	left SRB sideslip (uncorrected for flow angular-ity), degrees
BETRSU	BETRSU	right SRB sideslip (uncorrected for flow angularity), degrees
DEINLR	DEINLR	right inboard elevon deflection (no load), degrees
de ø nlr	DE Ø NLR	right outboard elevon deflection (no load), degrees

SYMBOL	MNEMONIC	DEFINITION

Model Geometric Nomenclature (Continued)

PHII PHII Tunnel Instrumentation indicated roll attitude, degrees

Pressure Data

CP BV	CPBV	vertical	tail base pressure coefficient
CPTXXX	CPTXXX	pressure	coefficient for tap XXX
CP1	CP1	See Data	Reduction Section
CP2	CP2	See Data	Reduction Section
CP3	CP3	See Data	Reduction Section
CP4	CP4	See Data	Reduction Section
CP5	CP5	See Data	Reduction Section
CP6	CP6	See Data	Reduction Section
CP7	CP7	See Data	Reduction Section
CP8	CP8	See Data	Reduction Section
CP9	CP9	See Data	Reduction Section
CP10	CP10	See Data	Reduction Section

Terms Used in Data Reduction

BW	wing bending moment about Y_0105 , in-1bs.
NW	wing normal force, lbs.
TW	wing torsion moment about X ₀ 1307, in-1bs.
BVT	vertical tail bending moment about $Z_{\rm O}503$, in-lbs.
NVT	vertical tail normal force, 1bs.

NOMENCLATURE (Concluded)

SYMBOL MNEMONIC	DEFINITION
TVT	vertical tail torsion moment about $X_01414.3$, in-lbs.
HEI	inboard elevon hinge moment, in-lbs.
нео	outboard elevon hinge moment, in-lbs.

REMARKS

A preliminary calibration at the Los Angeles Division of Rockwell International of the three-component balance for the right wing indicated that the torsion gauge sensitivity was below the normally acceptable level for this type of balance. Therefore, prior to the AEDC calibration, the beam was regauged by AEDC to increase the torsion sensitivity. During the test large zero shifts were encountered. Check loads showed that there was fouling between the wing and the fuselage. Repeated attempts were made during the test to clear the fouling, but all sources of fouling were not identified until after the test. All wing data where zero shifts occurred were recomputed using post-run balance zeros. Because of the problems encountered during the test, extreme caution is recommended when using and interpreting wing coefficient data.

During the test various events occurred having a possible effect on the test results. These items are noted below.

- 1. On part numbers 801 through 889, there was tape over the elevon (inboard and outboard) beam/bracket joint line.
- 2. On part numbers 801 through 1121, a loose wire connection which could affect wing data was found on the wing torsion gauge.
- 3. On part number 1096, point 4 and part number 1097, point 1, the transducer constant for scanivalve number 5(KSV5) in the external tank was wrong. A value of 290 was substituted for these points.
- 4. On part numbers 1132 through 1188, 1201 through 1216, and 1224 through 1314, the transducer constant (KSV5) was intermittently out of tolerance (high by as much as 10 percent). The reason for this condition was never determined. CP7 data should be used with caution when KSV5 is out of tolerance.

REMARKS (Concluded)

- 5. On part numbers 1188 through 1200, base pressure instrumentation for the ET and SRB's was inoperative. Equivalent base correction terms (CP5, CP6, CP7, and CP9) from part numbers 1141 through 1153 were substituted.
- 6. On part numbers 1224 through 1233, there was tape across the vertical tail/rudder joint line.
- 7. On part numbers 1377 through 1396, the right hand inboard elevon deflection angle was set at 8 degrees rather than 10 degrees, as called for in the run schedule. These runs were repeated with the correct elevon angle (part numbers 1432 through 1451).
- 8. Data from several pressure taps were bad for various reasons at different times during the test. The data in question were eliminated from the average in the base pressure correction calculations. The part numbers, pressure tap numbers, and correction coefficients affected are given below.

Part Numbers	Pressure Tap Number	Term Affected
1042-1073	438	CP2
1042-1073	439	CP2
1042-1111	406	CP2
1042-1121	1521	CP7
1399-1419	311	CP1
1399-1419	312	CP1

CONFIGURATIONS INVESTIGATED

The model for the AEDC-PWT test period was an 0.02-scale replica of the Rockwell International first stage space shuttle vehicle consisting of orbiter, external oxygen/hydrogen tank (ET) and two solid boosters (SRB's). The vehicle is described by the VC70-000002 configuration control drawing. The integrated vehicle geometry is shown in Figure 2a. The model was mounted upright in the tunnel through the base of the orbiter using the AEDC 2.5-inch Task MK XXXI balance (AEDC 6-2.5-2.5-1.85-M-C balance). Photographs of the model in the tunnel and of model details are given in Figures 3a through 3e.

The external tank and boosters were supported from the orbiter/ET attach structure using the AEDC-PWT-6-1.50-1.80-1.12 M balance. Each SRB was supported from the ET/SRB attach structure using the AEDC-PWT-6-1.50-0.50-1.12 M-a and -b (one in each SRB) balances. The orbiter balance measured total vehicle loads; the external tank balance measured ET/SRB loads, exclusive of the attach structure between orbiter and external tank; each SRB balance measured only the forces and moments on the element in which it was mounted, exclusive of attach hardware.

The orbiter was fabricated to the OV102 Configuration Outer Mold Line Definition (March 15, 1976 CML configuration). Lines were derived from the design entry trajectory 14414.1, Revision C/C. The Thermal Protection System (TPS) for these lines is based on the useage of Silicon Reuseable Surface Insulation (SRSI). The orbiter model is of a blended wing/body design with a double delta planform (81°/45° leading

edge) wing of 12 percent thickness and full span elevons with gaps between the outboard and inboard panels and between the inboard panel and the fuselage. A single centerline vertical tail with rudder/speed brake capability is mounted between the Orbital Maneuvering System (CMS) pods on the aft fuselage, and a body flap is fitted to the lower trailing edge of the fuselage. The Main Propulsion System (MPS) nozzles were simulated, but were trimmed to clear the sting support though the base. The CMS nozzles and all Reaction Control System (RCS) thruster ports in the forward fuselage and CMS pods were simulated.

Fuselage Outer Mold Line (CML) penetrations and protuberances which are simulated include:

- Recessed windshields, hatch, and observation windows
- Simulated forward and aft RCS nozzles
- Cargo bay door hinges
- T-zero umbilical panels
- Vents: cargo bay, wing, OMS RCS, and aft fuselage
- Spanwise steps: Vertical tail/rudder and body flap

The upper surface flipper door panels which blend the wing to the elevon at all deflections were not simulated. A smooth fairing between wing and elevon upper surfaces simulated the flipper door panel. The OV102 Shuttle Infrared Leeside Temperature Sensing (SILTS) pod was simulated on the vertical tail. The orbiter model was constructed primarily of Armco 17-4 stainless steel, with 7076-T6 aluminum used in

some non-load carrying components. The mid/aft upper fuselage is fabricated from a single block with a longitudinal bore into which balance adapters can be inserted. The CMS pods are an integral part of this block. The nose/forward fuselage was fabricated as a hollow shell and serves as a cover plate for model-mounted instrumentation.

The vertical tail was supported on the upper aft fuselage by means of a strain gauged beam (three-component balance). The rudder/speed brake, fixed at zero degrees deflection was mounted on a gauged beam to allow for measurement of hinge moments. A separate base plate/lower aft fuselage block incorporated the aft CMS/RCS pods, the simulated MPS and CMS nozzles, and the body flap bracket recesses. The base plate and MPS nozzles were cut out for sting clearance. The body flap was mounted at zero degrees deflection.

The right wing, right wing glove, and lower fuselage aft of station 520 was fabricated as a single piece. The left wing/wing-glove was cut off at butt plane 105 and was attached to the lower fuselage by a strain gauged beam (three-component balance). A labyrinth seal was used along the gap between the two parts to minimize leakage between upper and lower surfaces.

The elevons on both wings were mounted on individual beams to allow for measurement of hinge moments. Although the beams on the right and left wings were dimensionally similar, only those on the right wing were gauged. The elevon deflection angles were set by manually changing the

brackets to which the beams are attached. Measured deflection angles are given in Table III. Upper surface seal doors (flipper doors) were not simulated but a fairing was used between the wing and the elevon. A gap of from 0.005 to 0.020-inches was maintained between the fairing and the elevon.

The external tank was built in accordance with Rockwell International Interface Control Drawing ICD2-00001, Rev. C, plus Interface Revision

Notices B and C. The external tank is of cylindrical cross-section with a nominal diameter of 333-inches and a maximum diameter of 336.2-inches.

The forward portion of the external tank has a tangent ogive nose which terminates in a biconic nose cap over the LOX vent valve. The forward one-third of the external tank is filled with LOX, and the aft two-thirds with liquid hydrogen. Structural stiffeners between the two vessels result in an area with a slightly larger than nominal diameter.

The aft end of the tank is basically an ellipsoid of revolution.

The entire external tank is covered with a spray-on foam insulation of varying thickness. Approximate thicknesses are 2.5-inches on the tangent ogive, 1.0-inch on the cylindrical sections, and 2.0-inches on the rear ellipsoid. Model dimensions included this insulation.

The external tank configuration included a number of protuberances consisting of electrical trays, fluid lines, and attach hardware.

Electrical trays which run parallel to the external tank centerline were simulated; those which run up next to the aft orbiter/external tank

attach hardware were not. The LOX and LH2 feed lines were simulated. The attach hardware that is considered as part of the external tank is the front and rear orbiter/external tank attach structure which remains with the external tank after separation.

The external tank model was constructed primarily of 6061-T651 aluminum alloy with the load carrying components made of Armco 17-4 stainless steel. The model was formed by three major pieces to which the external protuberances were mounted. The three major pieces consisted of the forward biconic nose, the central cylindrical shell and the aft closure. The external tank protuberances and simulated aft attach structures were fabricated from Armco 17-4 stainless steel and were secured to the tank by mounting buttons and silver solder.

The external tank was attached to the crbiter by the "wishbone" attach bracket on the forward end and the simulated LOX and LH2 vertical feed lines on the aft end. These components were scaled to as great a degree as possible, but were sized for the anticipated loads. The orbiter/external tank attach structure was connected directly to the balance bridge inside the external tank. Instrumentation leads from the external tank to the orbiter were attached to the back of each feed line and were covered with a fairing. The external tank wall in the vicinity of the attach structure was cut away for clearance between the tank, and the structure and fairing. The resultant gap was filled with foam.

The Solid Rocket Boosters (SRB's) were built to the same Interface

Control Drawing (ICD2-00001, Rev. C) and Interface Revision Notices (B and C) as the external tank. The two SRB's are 146-inch diameter cylinders, each with an 18 degree semi-angle nose terminated by a 13.27-inch diameter sphere. An 18 degree flared skirt, 208.20-inches in diameter, protects the rocket nozzle. A flexible donut-shaped seal and thermal shield is provided between the skirt and the nozzle. SRB protuberances consist of a forward attach lug, front and rear separation motors, an aft attach ring, various stiffeners, and a full-length electrical systems tunnel.

The Solid Rocket Boosters were made of Armco 17-4 PH stainless steel, except for the forward cylindrical shells which were made of 6061-T651 aluminum alloy. Each SRB was formed by five major pieces to which the external protuberances were mounted. The five major pieces were the nose, the forward and the center cylindrical shells, the aft cylindrical shell/skirt assembly and the nozzle. The center cylindrical shells were fabricated with a vertical split to facilitate assembly and disassembly of the SRB. The SRB protuberances were fabricated from aluminum alloy and stainless steel, and were secured to the SRB with screws or silver solder. Each SRB is attached to the ET at the full-scale attach points. Attach structure components were scaled to as great a degree as possible, but were sized for the anticipated loads. The SRB/ET attach structure was connected directly to the balance bridge inside the SRB.

Instrumentation leads from the SRB to the external tank were routed through a slot aft of the forward SRB/ET attach post. A fairing between the SRB and the ET protected the leads from the air flow. The SRB wall in the vicinity of the SRB/ET attach structure was relieved for clearance between the SRB, and the attach structure and fairing. The resultant gap was filled with foam.

The following nomenclature. illustrated in Figures 2i through 21, was used to designate model components:

Symbol	Description
B ₇₅	OV102 fuselage including T-zero umbilical panels and crew hatch
c ₁₆	Canopy including recessed windshields and observation windows
E64	Elevons. including elevon/elevon and elevon/fuselage gaps
F ₁₆	Body flap
FR ₂₂	Fairings for the forward cargo bay door hinges, 6 per side
HG ₁	Cargo bay door hinges, 13 per side
M ₅₂	CMS pods
N_{108}	Forward RCS thruster nozzle ports
N ₁₀₉	Main propulsion system nozzles (inner surfaces cut away for sting clearance)
N_{110}	QMS nozzles
N_{lll}	Aft RCS thruster nozzles and ports
R ₂₀	Rudder, split into left and right speed brake panels

Symbol	Description
\mathbf{u}_{1}	Umbilical doors
v ₂₇	Vertical tail
v ₂₉	Vertical Tail with OV102 SILTS pod
v T ₁₀	Cargo bay vents, 4 per side
VTll	Wing/landing gear bay vents, 1 per side
v_{14}	Aft fuselage vents, l per side
v 17	Miscellaneous vents, ports and penetrations
W ₁₃₁	OV102 Wing
T ₃₉	External tank, including all protuberances (See ICD2-00001, Rev. C)
S ₂₇	Solid rocket booster, including all protuberances (See ICD2-00001, Rev. C)

TEST FACILITY DESCRIPTION

The AEDC PWT 16-Ft. Transonic Tunnel (Propulsion Wind Tunnel, Transonic 16T) is a continuous-flow closed-circuit tunnel capable of operation within a Mach number range of 0.20 to 1.60. The tunnel can be operated within a stagnation pressure range of 120 to 4000 psfa depending upon the Mach number. The stagnation temperature can be varied from an average minimum of about 80 to a maximum of 160°F as a function of cooling water temperature. Using a special cooling system of mineral spirits, liquid nitrogen, and liquid air, the stagnation temperature range can be varied from +30 to -30°F. Supersonic velocities are obtained by use of flexible-wall, Laval type nozzles.

The test section is 16-ft. square (in cross section) and 40-ft. long. The entire test section and supporting structure is constructed as a separate unit, called the test section cart, and is removable from the tunnel circuit. The test section carts may be moved to the model installation building where the test article and associated equipment are installed.

Two 40-ft. long test section carts are available for testing throughout the design temperature range. These carts are each 20-ft. long and are used in pairs to form the 40-ft. long test section. Each cart may be used in either the forward or aft position in the test section.

The test section is completely enclosed in a plenum chamber which can be evacuated, allowing part of the tunnel main flow to be removed

TEST FACILITY DESCRIPTION (Concluded)

through the test section perforated walls, thereby unchoking the test section at near sonic speeds and alleviating wall interference effects.

TEST PROCEDURE

The Hi-Pitch model support system was used for the 0.02-scale force model test entry. This support system has the capability of pitch rates up to 8 deg/sec and roll rates exceeding 20 deg/sec. A pitch rate of approximately 1 deg/sec and a roll rate of 20 deg/sec was selected for this test. Sketches and photographs showing the 0.02-scale model supported on the Hi-Pitch system are shown in Figures 2g and 3a.

The Hi-Pitch support system was mounted into a dummy roll mechanism of the standard sting support system and utilized the vertical traverse feature of the latter system to maintain the model as close to tunnel centerline as possible within the physical constraints of +36 inches vertical traverse of the standard sting support system. This limitation placed the orbiter approximately 9 inches below tunnel centerline at sting pitch angles of 0 degrees or greater and 32 inches below tunnel centerline at a sting pitch angle of -10 degrees. Model angles-of-attack and sideslip were established by computer control utilizing the hydraulic motors of the Hi-Pitch system to position the sting at appropriate pitch and roll angles.

The test of the 0.02-scale launch vehicle was concerned primarily with force and moment measurements and the only pressures measured were those located on the bases of the model components. These pressure locations are shown in Figures 2b through 2f and are categorized as follows:

TEST PROCEDURE (Continued)

Major Model Component	Model Component	No. of Orifices
Orbiter	Base	19
Orbiter	Body Flap	32
External Tank	Base	45
Solid Rocket Boosters	Base	10
	Total	106

The types of balances utilized, and the model forces and moments calculated from their measurements are given below. The balances are described in detail in Reference 1.

Balance Location	Туре	Model Forces and Moments Measured or Calculated
DOCUMENT	<u> </u>	
Orbiter	6-component	Launch vehicle normal force, side force, axial force, pitching moment, yawing moment, and rolling moment
External Tank	6-component	ET and SRB's normal force, side force, axial force, pitching moment, rolling moment, and yawing moment
Left Hand Solid Rocket Booster	6-component	Left hand SRB normal force, side force, axial force, pitching moment, rolling moment, and yawing moment
Right Hand Solid Rocket Booster	6-component	Right hand SRB normal force, side force, axial force, pitching moment, rolling moment, and yawing moment
① _{Wing}	3-component	Wing normal force, bending moment, and torsional moment
Verti cal S ta bilizer	3-component	Vertical stabilizer side force, bending moment, and torsional moment

① Wing balance data judged unreliable because of the model-balance fouling.

TEST PROCEDURE. (Concluded)

Balance		Model Forces and Moments Measured
Location	<u>Type</u>	or Calculated
Rudder	1-component	Rudder hinge moment
Inboard Elevon	1-component	Inboard elevon hinge moment
Outboard Elevon	1-component	Outboard elevon hinge moment

Pitch and roll angles of the Hi-Pitch Support System sting were calculated from the outputs of potentiometers. Electrical signals from all position measuring devices, balances, and Scanivalve R transducers were digitized for data reduction. All coefficient data were tabulated on-line.

The desired tunnel conditions, given in Table I, were set and angleof-sideslip was varied at a nominal constant angle-of-attack. During the
acquisition of pressure data, computer evaluation of the pressure rate-ofchange was utilized and the transducer output was not acquired for computational purposes until either the rate of change was within acceptable
limits or a maximum time delay was reached. Force and moment data were
acquired following the acquisition of the pressure data.

Check loads were placed on the gaged elevons prior to, and following each change in elevon deflection angles, and data were obtained through the computer to verify the calculation of the applied loads. The nominal and measured elevon deflection angles that were tested are given in Table III and a sketch showing the direction of positive elevon deflection is presented in Figure 1b.

DATA REDUCTION

All measured pressures were converted into standard pressure coefficient form and were tabulated "on-line" at the test facility. Base pressure corrections were made to normal force, axial force, and pitching moment coefficients. In addition, axial force of the external tank and axial force and yawing moment from both solid rocket boosters were corrected for base pressure effects.

Force and moment coefficient data were computed in the body axis coordinate system (See Figure la) from the balances located in the orbiter, external tank, and both solid rocket boosters using the projection of the orbiter nose on the external tank longitudinal centerline as the moment reference point location. Forces and moments from the wing, vertical stabilizer, and elevons were computed about moment reference points unique to the individual model components. The location of the moment reference points and directions of positive forces and moments are shown in the sketches of Figures 1b through 1f.

Flow angularity corrections were applied to all test data. The magnitude of these corrections is shown in Figure 2h. These corrections were determined from the testing accomplished on the Hi-Pitch model support system and indicate its dependence on vertical location in the test section. The flow angularity investigation was conducted only at sting pitch angles of -6, 0, and 6 degrees, and although a large change in pitch-plane flow angularity was determined between 0 and -6 degrees, it was felt that extrapolation of AFA at the same rate of change beyond

DATA REDUCTION (Continued)

-6 degrees was not warranted. The values of BFA depicted in Figure 2h were those determined during a previous flow angularity calibration at M = 0.90 for the portion of the test section occupied by the model at the various sting pitch angles. The corrections of Figure 2h were input to the calculations of model angles-of-attack and sideslip as functions of model roll orientation.

Pressure coefficients required for base pressure adjustments were computed as follows:

$$CP3 = (1/6) (CPT319 + CPT320 + CPT321 + CPT322 + CPT323 + CPT324)$$

$$CP4 = (1/2) (CPT325 + CPT326)$$

$$CP5 = (1/4) (CPT2202 + CPT2204 + CPT2221 + CPT2222)$$

$$CP6 = CPT2225$$

CP7 = (0.1629) (7/12)
$$\sum_{i=1501}^{1507} \text{CPT}_i + (0.1629/12)$$
 (CPT1509)

+ (0.1629) (4/12)
$$\sum_{i=1511}^{1514} \text{CPT}_i$$
 + (0.0936) (6/11) $\sum_{i=1516}^{1521} \text{CPT}_i$

DATA REDUCTION (Continued)

where

CPTi is the pressure coefficient for pressure tap i.

Base pressure adjustments to the force and moment coefficients were computed as follows from the pressure coefficients derived above.

For the Orbiter:

For the left SRB: CABLS = (-1/SREF) [(CP5) (A5) + (CP6) (A6)] CYNBLS = -(YS/LREF) (CABLS)For the right SRB: CABRS = (-1/SREF) [(CP9) (A9) + (CP10) (A10)] CYNBRS = (YS/LREF) (CABRS)These adjustments were applied to the measured force and moment coefficients to give forebody coefficients. For the launch vehicle (orbiter balance): CNFL = CNL - CNBO CLMFL = CLML - CLMBO CYFL = CYLCYNFL = CYNL - CYNBLS - CYNBRS CAFL = CAL - CABO - CABT - CABLS - CABRS CBLFL = CBLL For the external tank and two SRB's (external tank balance): CNFTS = CNTS CLMFTS = CIMTS CYFTS = CYTS

CAFTS = CATS - CABT - CABLS - CABRS

CYNFTS = CYNTS - CYNBLS - CYNBRS

CBLFTS = CBLTS

For the left SRB (left SRB balance):

CNFIS = CNIS

CLMFLS = CLMLS

CYFLS = CYLS

CYNFIS = CYNLS - CYNBIS

CAFLS = CALS - CABLS

CBLFIS = CBLLS

For the right SRB (right SRB balance):

CNFRS = CNRS

CLMFRS = CLMRS

CYFRS = CYRS

CYNFRS = CYNRS - CYNBRS

CAFRS = CARS - CABRS

CBLFRS = CBLRS

For orbiter alone forebody data:

CNFO = CNFL - CNFTS

CLMFO = CLMFL - CLMFTS

CYFO = CYFL - CYFIS

CYNFO = CYNFL - CYNFTS

CAFO = CAFL - CAFTS

CBLFO = CBLFL - CBLFTS

The external tank alone forebody coefficients were computed as:

CNFT = CNFTS - CNFLS - CNFRS

CIMFT = CIMFTS - CIMFLS - CIMFRS

CYFT = CYFTS - CYFLS - CYFRS

CYNFT = CYNFTS - CYNFLS - CYNFRS

CAFT = CAFTS - CAFLS - CAFRS

CBLFT = CBLFTS - CBLFLS - CBLFRS

The panel loads were reduced to force and moment coefficients in the following manner:

For wing bending and torsion:

CNW = NW/[(Q) (SREF)]

CBW = BW/[(Q) (SREF) (BREF)]

CTW = TW/[(Q) (SREF) (MAC)]

For vertical tail bending and torsion:

CNVT = NVT/[(Q) (SVT)]

CBVT = BVT/[(Q) (SVT) (CVT)]

CTVT = TVT/[(Q) (SVT) (CVT)]

For elevon hinge moments:

CHEI = HEI/[(Q) (SE) (CE)]

CHEO = HEO/[(Q) (SE) (CE)]

For rudder hinge moments:

CHR = HR/[(Q) (SR) (CR)]

Uncertainties (a statistical combination of systematic and random errors) of the tunnel freestream properties, aerodynamic coefficient uncertainties and pressure coefficient uncertainties are all presented in detail in Reference 2. A schedule of completed runs is given in Table II which is the Data Set/Run Number Collation Summary for the test.

Reference dimensions and constants used were:

	Valu	le	
Symbol	Model Scale	Full Scale	<u>Description</u>
Al	0.12576 ft. ²		Base area #1 (orbiter, including sting cavity area).
A2	0.0572 ft. ²		Base area #2 (projected body flap).
A3	0.049048 ft. ²		Base area #3 (OMS pods).
A 5, A 9	0.04661 ft. ²		SRB Skirt base areas, each.
A6, A10	0.04795 ft. ²		SRB Nozzle base area, each.
A7	0.24192 ft. ²		Base area of the external tank.
ACO	0.0377 ft. ²		Orbiter sting cavity area.
BREF	18.734 in.	936.7 in.	Wing bending reference length.
CE	1.814 in.	90.7 in.	Elevon reference chord length.
CR	1.464 in.	73.2 in.	Rudder reference chord length.
CVT	3.996 in.	199.8 in.	Vertical tail reference chord length.
Ll	25.260 in.	1263.0 in.	Horizontal transfer distance between the orbiter base and the integrated vehicle moment reference center.

DATA REDUCTION (Concluded)

	Valu	ıe	
Symbol	Model Scale	Full Scale	Description
L2	26.594 in.	1329.7 in.	Horizontal transfer distance between the body flap and the integrated vehicle moment reference center.
LREF	25.806 in.	1290.3 in.	Reference length.
MAC	9.496 in.	474.8 in.	Mean aerodynamic chord.
SE	0.084 ft. ²	210. ft. ²	Elevon reference area.
SR	0.04006 ft. ²	100.15 ft. ²	Rudder reference area.
SREF	1.076 ft. ²	2690. ft. ²	Wing reference area.
SVT	0.1653 ft. ²	413.25 ft. ²	Vertical tail reference area.
Y S	5.010 in.	250.5 in.	Lateral transfer distance between the SRB base and the integrated vehicle moment reference center.
Zl	6.730 in.	336.5 in.	Vertical transfer distance between the total orbiter base area and the integrated vehicle moment reference center.

REFERENCES

- 1. SD77-SH-0195, "Pretest Information for Test IA156A of the 0.02-Scale Model 89-OTS Space Shuttle Integrated Vehicle in the AEDC Propulsion Wind Tunnel (16T)," dated August 4, 1977.
- 2. AEDC-DR-78-25, "Documentation of Wind Tunnel Tests of the NASA Space Shuttle Launch Vehicle Models," dated March 16, 1978.
- 3. ARO, Inc. Letter of April 9, 1980 to D. E. Poucher from J. A. Black, subject, "Recomputed Space Shuttle Data from NASA/Rockwell Tests IA-105A, IA-156A, IA-105AR, IA-182, IA-183 (Project P43T-09)."
- 4. Rockwell International IL No. SAS/AERO/78-014, "Correction Requirements for IA105/156 Force and Moment Data," (April 25, 1978).

TABLE I. TEST CONDITIONS

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0.92 0.94 0.95		605 615 620	
0.96 0.97 0.98		622 625 630	
0.99 1.1 1.02		634 643 644	
1.03 1.04 1.05		647 652 655	
1.06 1.08 1.10		658 662 6 7 0	
1.15 1.20 1.25		684 700 710	
1.30 1.40 1.55	3.2 x 10 ⁶	717 735 684	
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TABLE II. (Continued)

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TABLE II. (Continued)

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TABLE II. (Continued)

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A) $\beta = 0.\pm 6^{\circ}$ COEFFICIENTS B) $\beta = 0.\pm 6^{\circ} \pm 10^{\circ}$ COEFFICIENTS D) $\beta = 0.\pm 4^{\circ} \pm 6^{\circ}$ E) $\beta = 0.\pm 6^{\circ} \pm 8^{\circ}$ NASA-WSFC-1	A) $\beta = 0.\pm 6^{\circ}$ COEFFICIENTS B) $\beta = 0, \pm 6^{\circ}, \pm 10^{\circ}$ C) $\beta = 0, \pm 4^{\circ}, \pm 6^{\circ}, \pm 8^{\circ}$ NASA-WSFC-1			4444	1	1	111	4	1	77	1	1	1	1	1	1 1 1	7	4	4
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TABLE II. (Continued)

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DAT	8 8 -7 0 0 2			25	111
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i		£8 E9		,	a or A SCHEDULES

TABLE II. (Continued)

FORCE DATASETS

- R8NV\$\$ Launch Vehicle Aerodynamic Coefficients
- R8NØ\$\$ Orbiter Aerodynamic Coefficients
- R8NW\$\$ Wing Data Coefficients
- R8NF\$\$ Pressure Data and Vertical Tail Data
- R8NM\$\$ Miscellaneous
- R8NT\$\$ ET Alone Aerodynamic Coefficients
- R8NS\$\$ ET + Left and Right SRB (ET balance)
- R8NL\$\$ Left SRB Aerodynamic Coefficients
- R8NR\$\$ Right SRB Aerodynamic Coefficients
- R8NN\$\$ Left SRB
- R8NP\$\$ Right SRB

PRESSURE DATASETS

- P4CE\$\$ Orbiter Base Coefficient of Pressure Data
- P4CF\$\$ Body Flap (Bottom) Coefficient of Pressure Data
- P4CG\$\$ Body Flap (Top) Coefficient of Pressure Data
- P4CL\$\$ Left SRB Base Coefficient of Pressure Data
- P4CR\$\$ Right SRB Base Coefficient of Pressure Data
- P4CT\$\$ ET Base Coefficient of Pressure Data

FORCE DATA - COEFFICIENT SCHEDULES

LAUNCH VEHICLE

Datasets R8NVOl thru 32, 34 thru 37, 40 thru 98, A0 thru E9

ALPHAØ BETAØ CNL CNFL CAL CAFL CLMFL CYFL CYNL CYNFL CBLFL

ORBITER

Datasets R8NØ01 thru 32, 34 thru 37, 40 thru 98, A0 thru E9

ALPHAØ BETAØ CNFØ CAPØ CLMFØ CYFØ CYNFØ CBLFØ CNBØ CABØ CLMBØ

WING

Datasets R8NWO1 thru 32, 34 thru 37, 40 thru 98, A0 thru E9

ALPHAØ BETAØ CNW CBW CTW CHEI CHEØ IB-ELV ØB-ELV PHII ALPHAI MACH

TABLE II. (Continued)

FORCE DATA - COEFFICIENT SCHEDULES (Continued)

VERTICAL TAIL

Datasets R8NFO1 thru 32, 34 thru 37, 40 thru 98, AO thru E9

ALPHAØ BETAØ CP1 CP2 CP3 CP4 CPBV RUDDER CHR CNVT
CBVT CTVT

MISCELLANEOUS

Datasets R8NMO1 thru 32, 34 thru 37, 40 thru 98, Ao thru E9

ALPHAØ BETAØ ALFAØU BETAØU PT P Q TT AFA BFA DEINLR
DEØNLR

EXTERNAL TANK

Datasets R8NTO1 thru 32, 34 thru 37, 40 thru 98, AO thru E9

ALPHAT BETAT CNFT CAFT CLMFT CYFT CYNFT CBLFT CABT
CP7 ALPHAØ BETAØ

(2) SOLID ROCKET BOOSTERS + EXTERNAL TANK

Datasets R8NSO1 thru 32, 34 thru 37, 40 thru 98, AO thru E9

ALPHAT BETAT CNFTS CATS CAFTS CLMFTS CYFTS CYNTS
CYNFTS CBLFTS ALFATU BETATU

LEFT SRB

Datasets R8NLO1 thru 32, 34 thru 37, 40 thru 98, AO thru E9

ALPHAL BETAL CNFLS CAFLS CLMFLS CYFLS CYNFLS CBLLS
CABLS CYNBLS CP5 CP6

RIGHT SRB

Datasets R8NRO1 thru 32, 34 thru 37, 40 thru 98, AO thru E9

ALPHAR BETAR CNFRS CAFRS CLMFRS CYFRS CYNFRS CBLRS
CABRS CYNBRS CP9 CP10

TABLE II. (Concluded)

FORCE DATA - COEFFICIENT SCHEDULES (Concluded)

LEFT SRB

Datasets R8NNO1 thru 32, 34 thru 37, 40 thru 98, A0 thru E9

ALPHAL BETAL CALS CYNLS ALFLSU BETLSU

RIGHT SRB

Datasets R8NPO1 thru 32, 34 thru 37, 40 thru 98, Ao thru E9

ALPHAR BETAR CARS CYNRS ALFRSU BETRSU

PRESSURE DATA - COMPONENTS

Datasets P4C\$01 thru 32, 34 thru 37, 40 thru 98, A0 thru E9 contain CP for taps located in the following components:

- \$ = E ORBITER BASE
 - F BODY FLAP BOTTOM
 - G BODY FLAP TOP
 - L LEFT SRB BASE
 - R RIGHT SRB BASE
 - T ET BASE

TABLE III. FLEVON DEFLECTION ANGLES

	$\delta_{ extsf{e}_{ extsf{I}}}$, deg	
Nominal	Left Hand Measured	Right Hand Measured
12	11.88	12.12
10	9.90	10.02
8	7.82	8.10

	$\delta_{e_{O}}$, deg	
Nominal	Left Hand Measured	Right Hand Measured
-7	- 6.95	- 6.88
- 2	-2.00	- 2.30
2	2.00	1.88
5	5.00	5.00
9	9.00	8.92
11	11.07	11.25





O_E

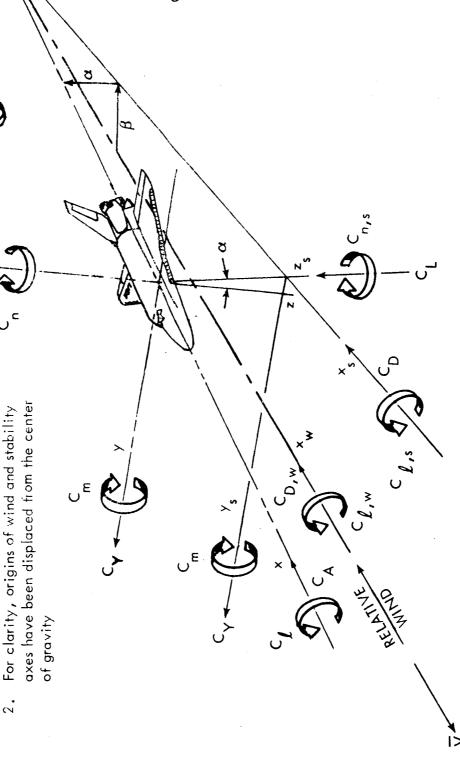
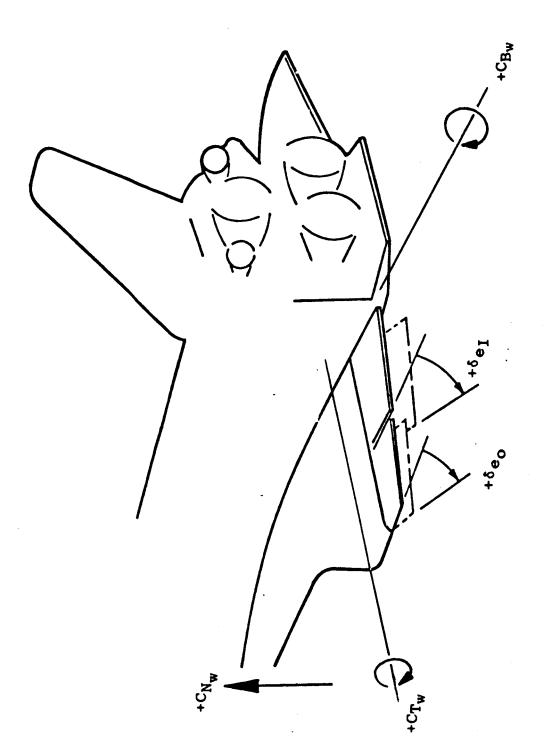
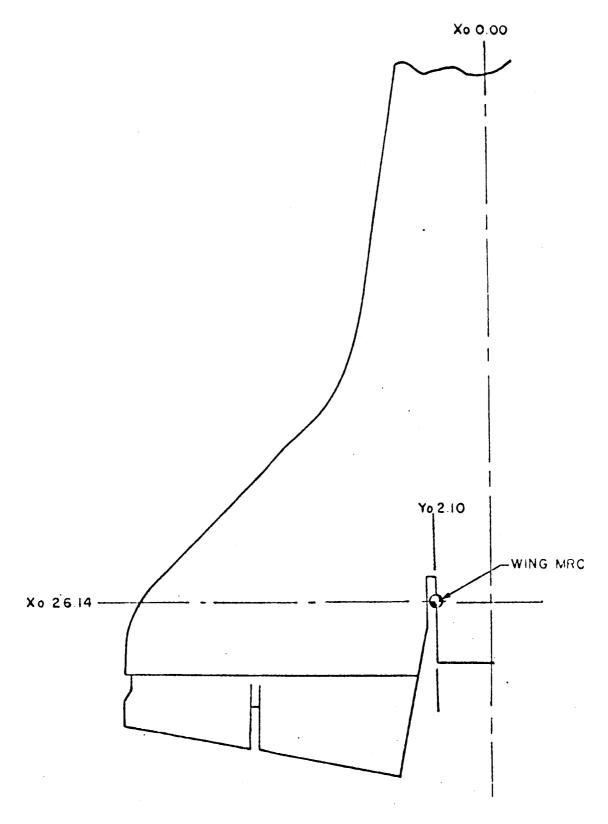


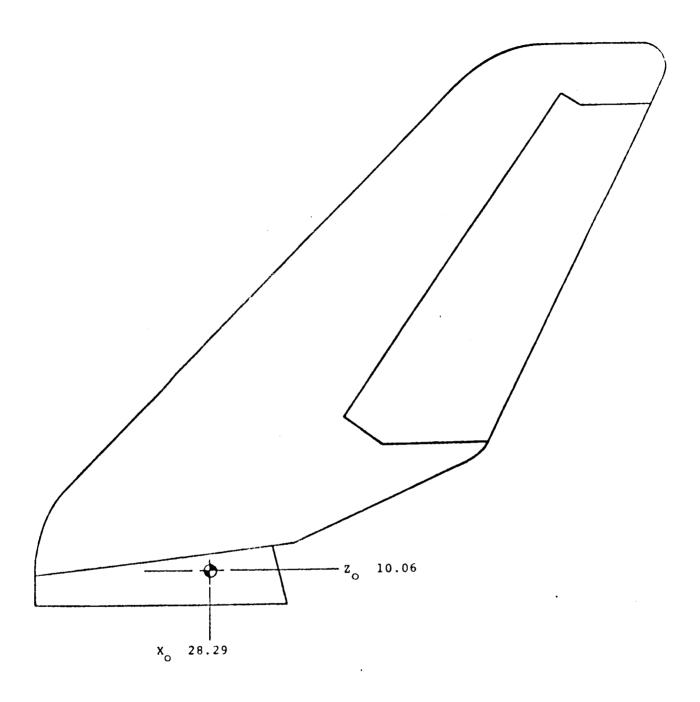
Figure 1. Model axis systems, sign conventions and reference dimensions. a. Axis Systems



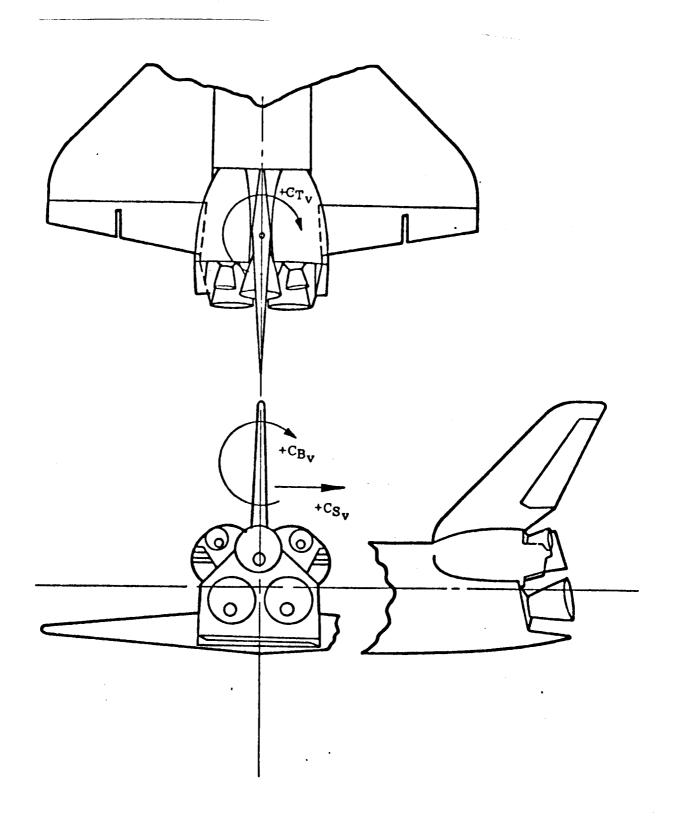
b. Definition of Deflection Angles and Wing Coefficients Figure 1. Continued.



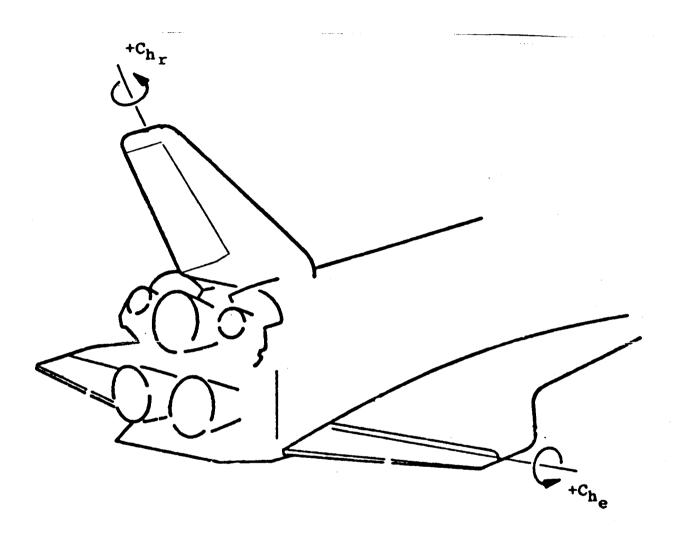
c. Wing Moment Reference Center Figure 1. Continued.



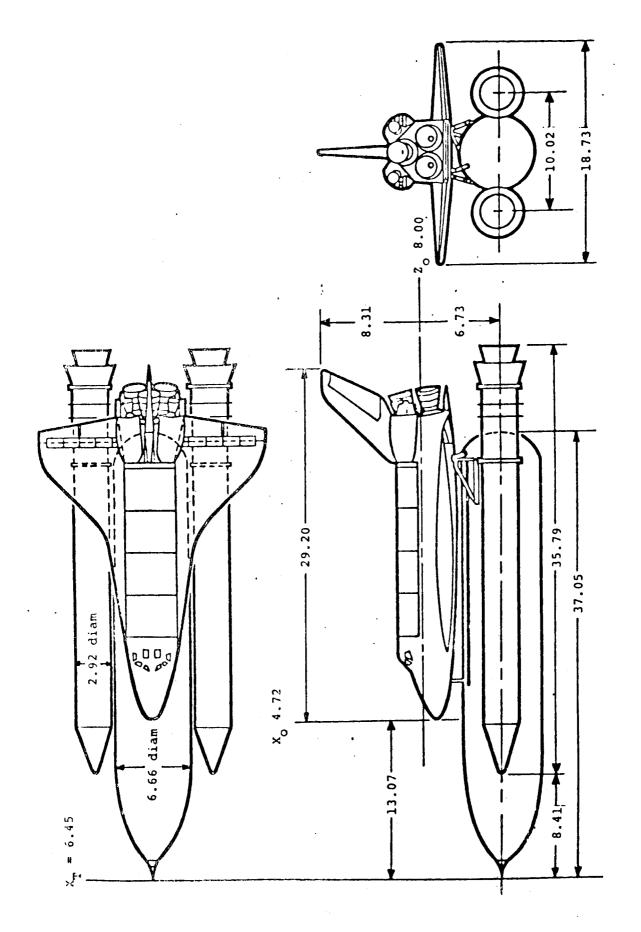
d. Vertical Stabilizer Moment Reference Center Figure 1. Continued.



e. Definition of Vertical Stabilizer Coefficients Figure 1. Continued.



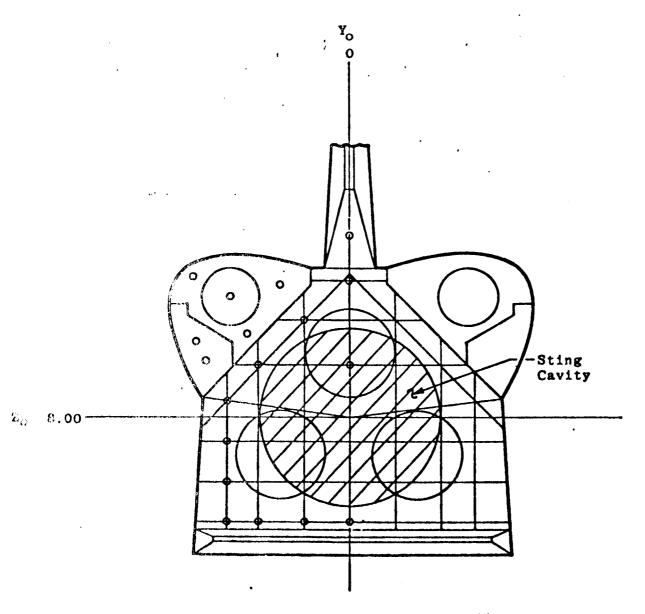
f. Definition of Elevon and Rudder Hinge Moment Coefficients Figure 1. Concluded.



a. Major Model Component Dimensions Figure 2. Model sketches.

Tap	z _o	Yo
301	10.64	0
302	10.1	0
306	6.04	0
308	9.56	-0.78
311	6.04	-0.76
312	8.78	-1.56
314	6.04	-1.56
315	8.28	-2.06
316	7.52	-2.06
317	6.8	-2.06

Tap	z _o	Yo
318 319 320 321 322 323 324 325 326	6.04 10.28 9.84 10.44 9.4 8.78 9.3 CAV	-2.06 -1.1 -1.76 -2.06 -1.92 -2.14 -2.6 0



b. Orbiter Base Pressure Orifice Locations Figure 2. Continued.

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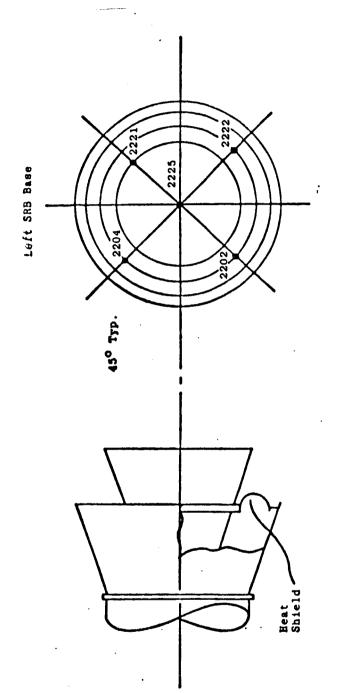
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3F	.60	407		415			439		Inches				_				•						.35
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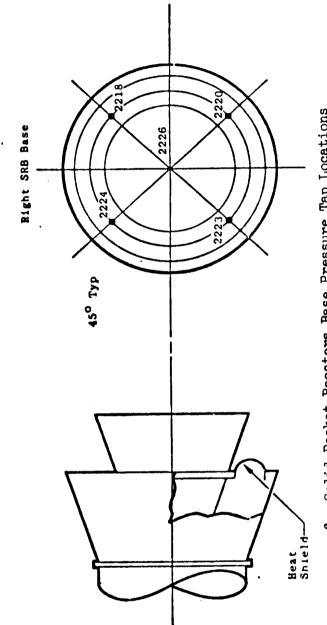
c. Orbiter Body Flap Top Surface Pressure Orifice Locations Figure 2. Continued.

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	.95	404		412	428	436		-		 							 .65
BF	.60	403		411		435	CBF = 1.62 Inches					•					•
X/CBF	. 20	402		410	426	434	1.62		-				+				 .50
	10	401		409		433	CBF =										.0
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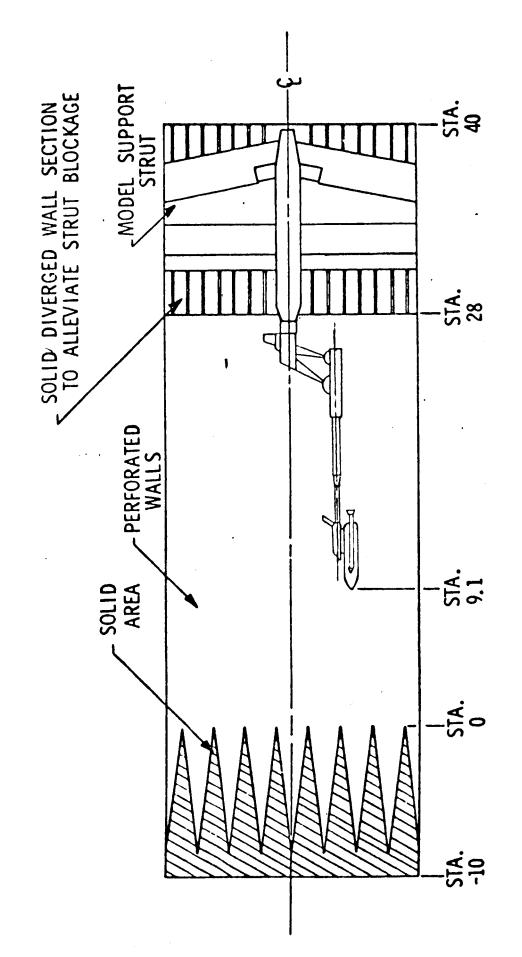
d. Orbiter Body Flap Bottom Surface Pressure Orifice Locations Figure 2. Continued.

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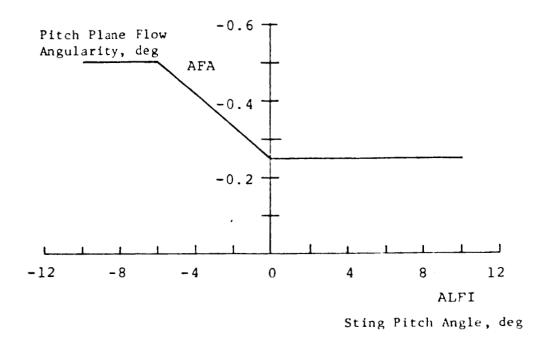


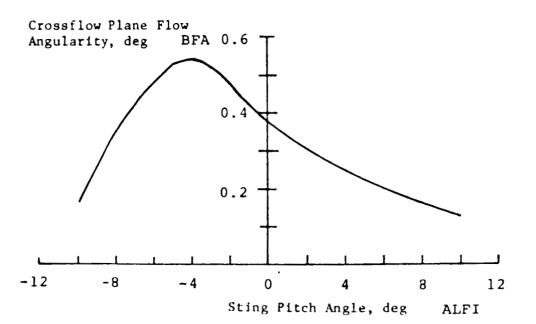


f. Solid Rocket Boosters Base Pressure Tap Locations Figure 2. Continued.

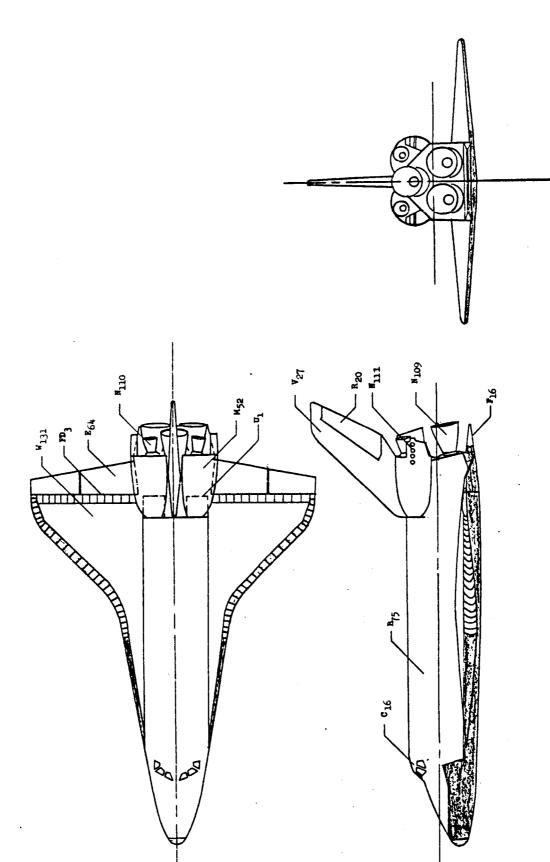


Sketch Showing Location of 0.02-Scale Model in the 16T Test Section Figure 2. Continued.

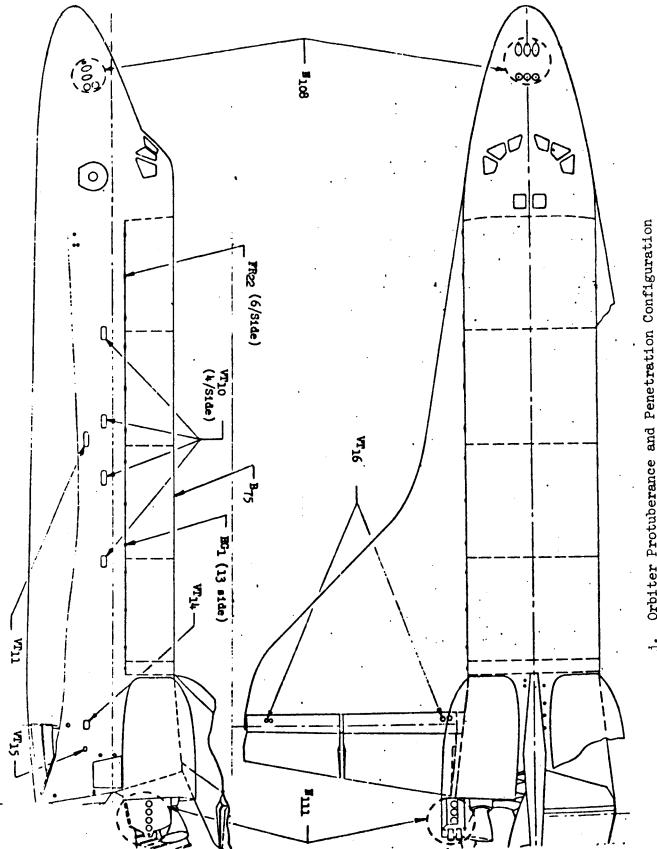




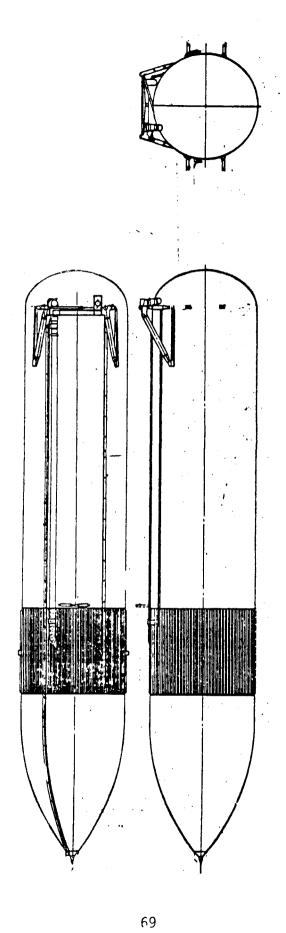
h. Pitch Plane and Cross-Flow Plane Flow Angularity Corrections for Hi-Pitch System Figure 2. Continued.



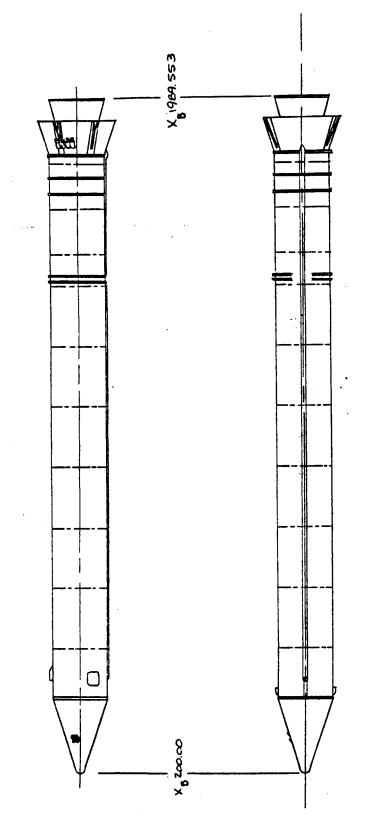
i. Orbiter Nomenclature Figure 2. Continued.



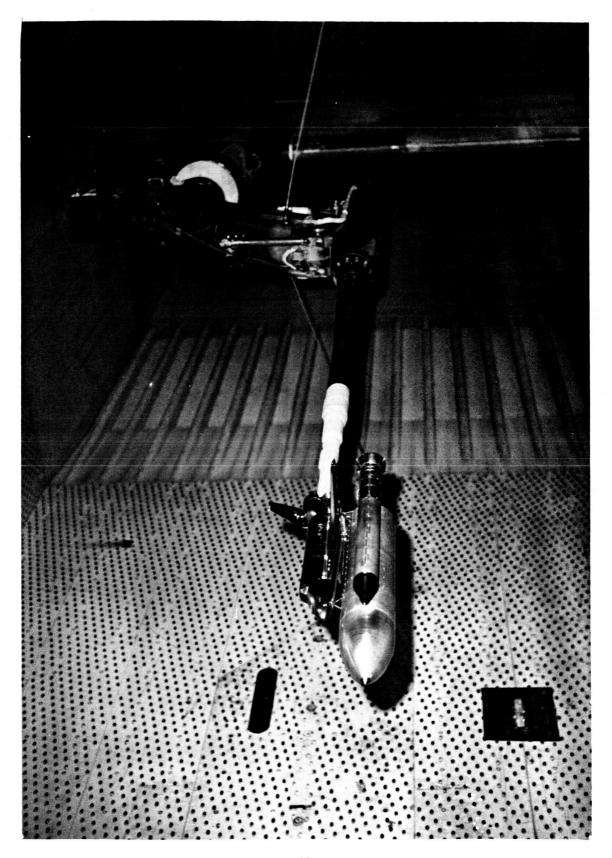
j. Orbiter Protuberance and Penetration Configuration Figure 2. Continued.



k. External Tank (T39) Figure 2. Continued.



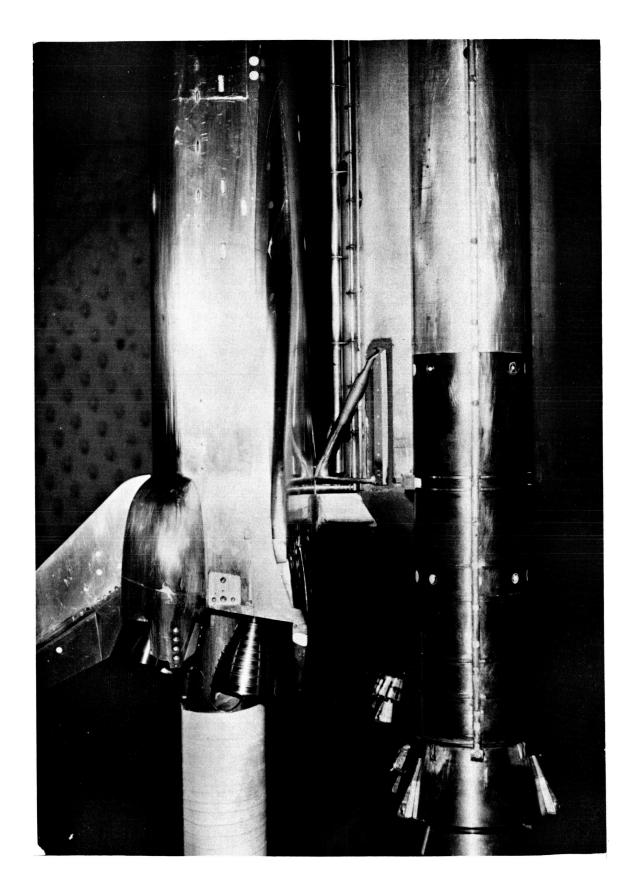
Solid Rocket Booster (S27)
 Figure 2. Concluded.



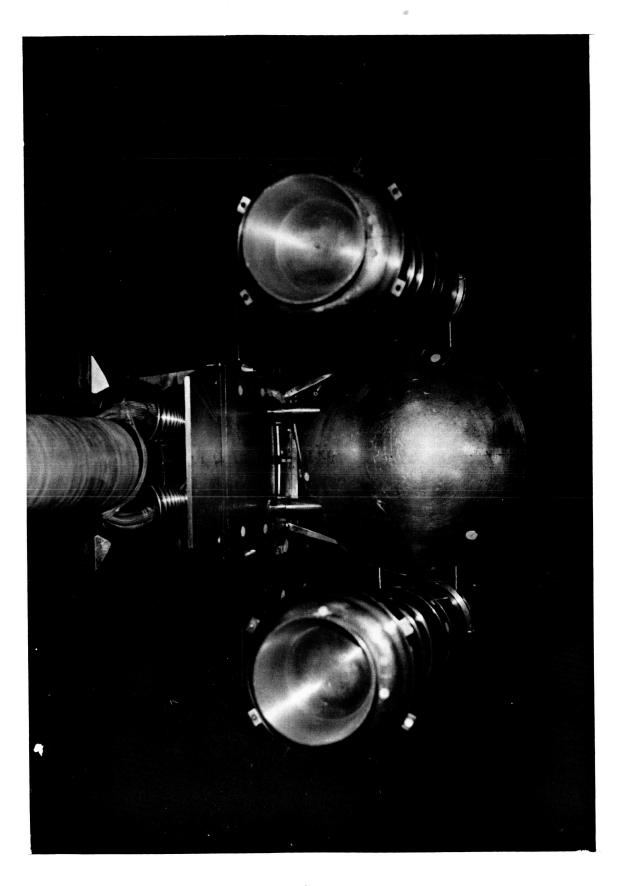
a. Model 89-OTS in the 16T Test Section Figure 3. Model photographs.

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c. Right-Rear View of Model 89-OTS, SILTS Pod Installed Figure 3. Continued.



d. Right-Rear Side View of Model 89-ORS. Note Instrumentation Fairings Behind Vehicle Feed Lines and Foam under Attach Structure Figure 3. Continued.



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 ${\tt APPENDIX}$

TABULATED SOURCE DATA